

Drifting acoustic measurements of tidal turbine radiated noise in an urban waterway

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Portsmouth, NH

95

Kittery

Memorial Bridge

Portsmouth

New Castle

NEW HAMPSHIRE

95



Living Bridge

Kittery

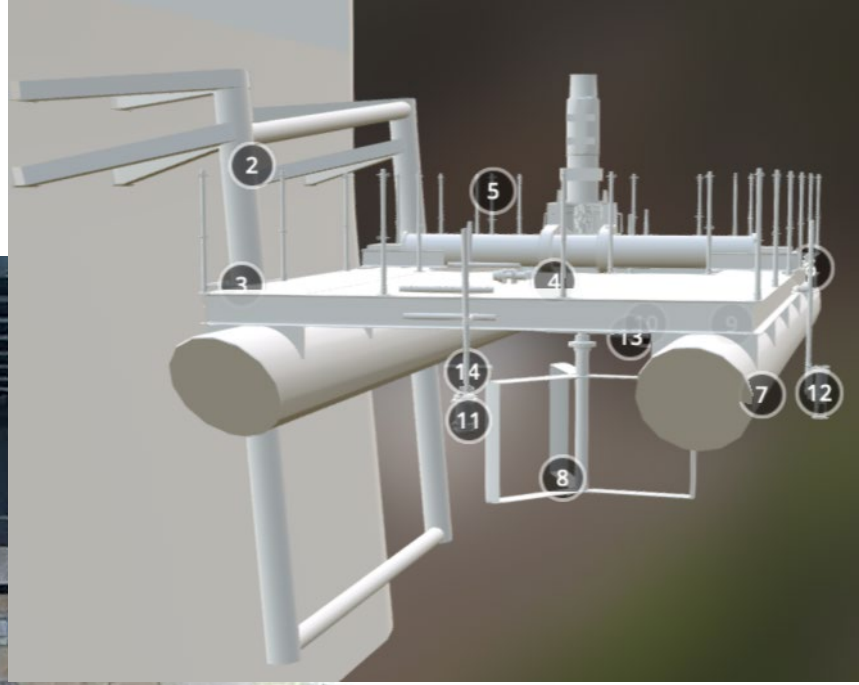
Piscataqua River

Memorial Bridge

Piscataqua River

Portsmouth

New Energy Cross-flow turbine

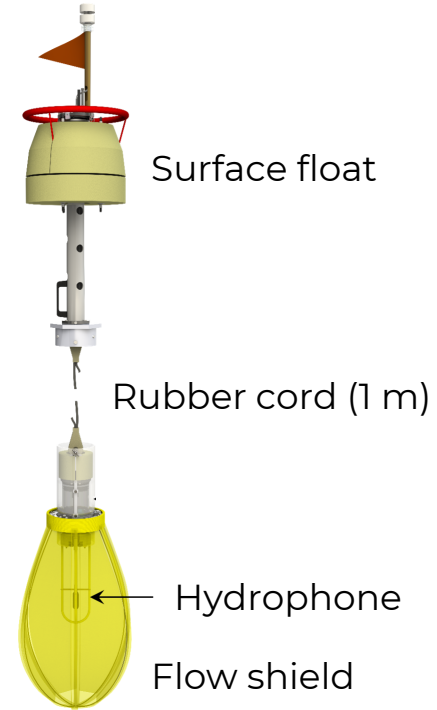


Images courtesy of
<https://livingbridge.unh.edu/>

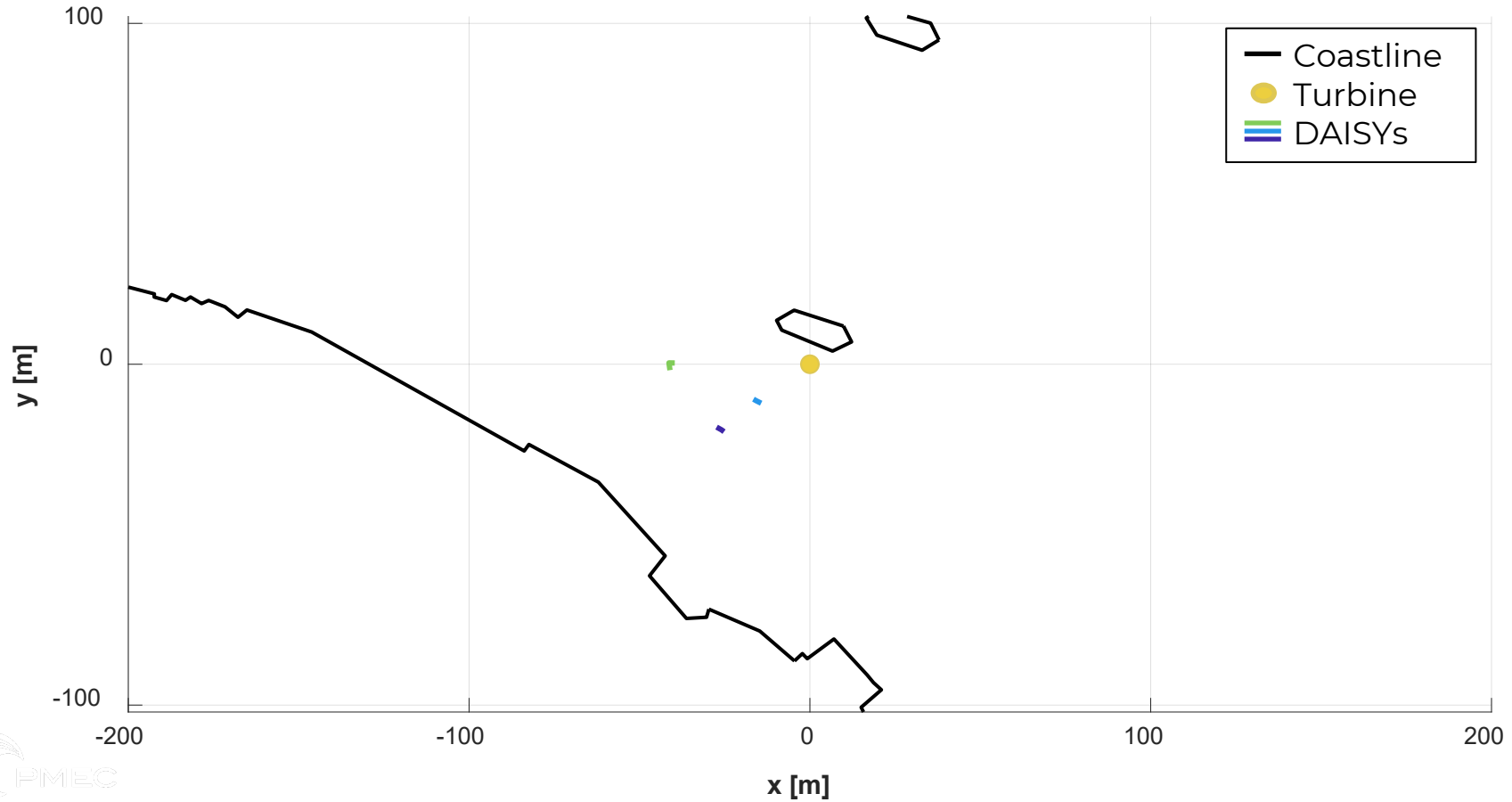
Goals

1. Measure noise from turbine
2. Evaluate potential for localization
3. Refine methodology (IEC TS 62600-40:2019)

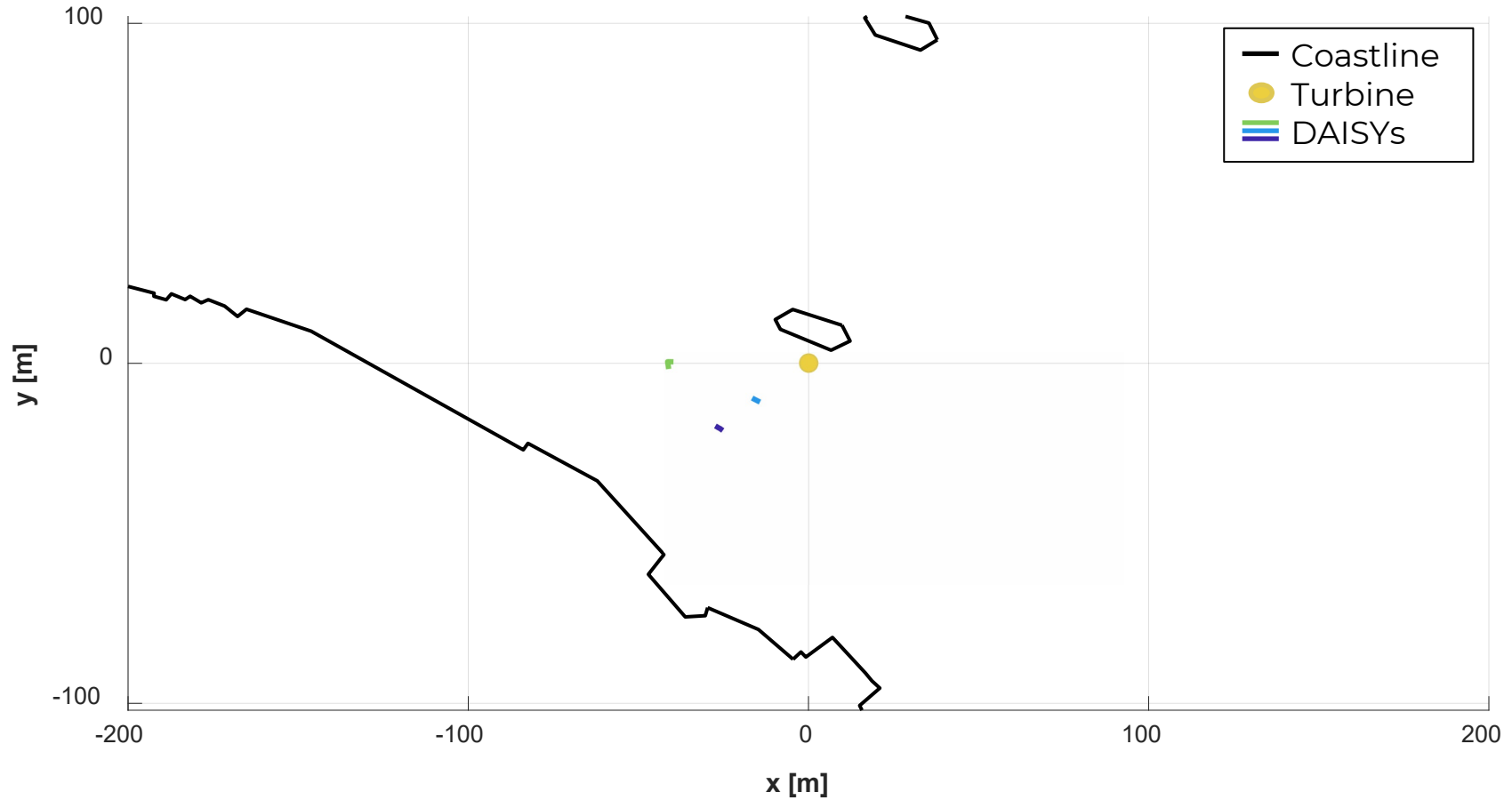
Drifting Acoustic Instrumentation **SY**stem



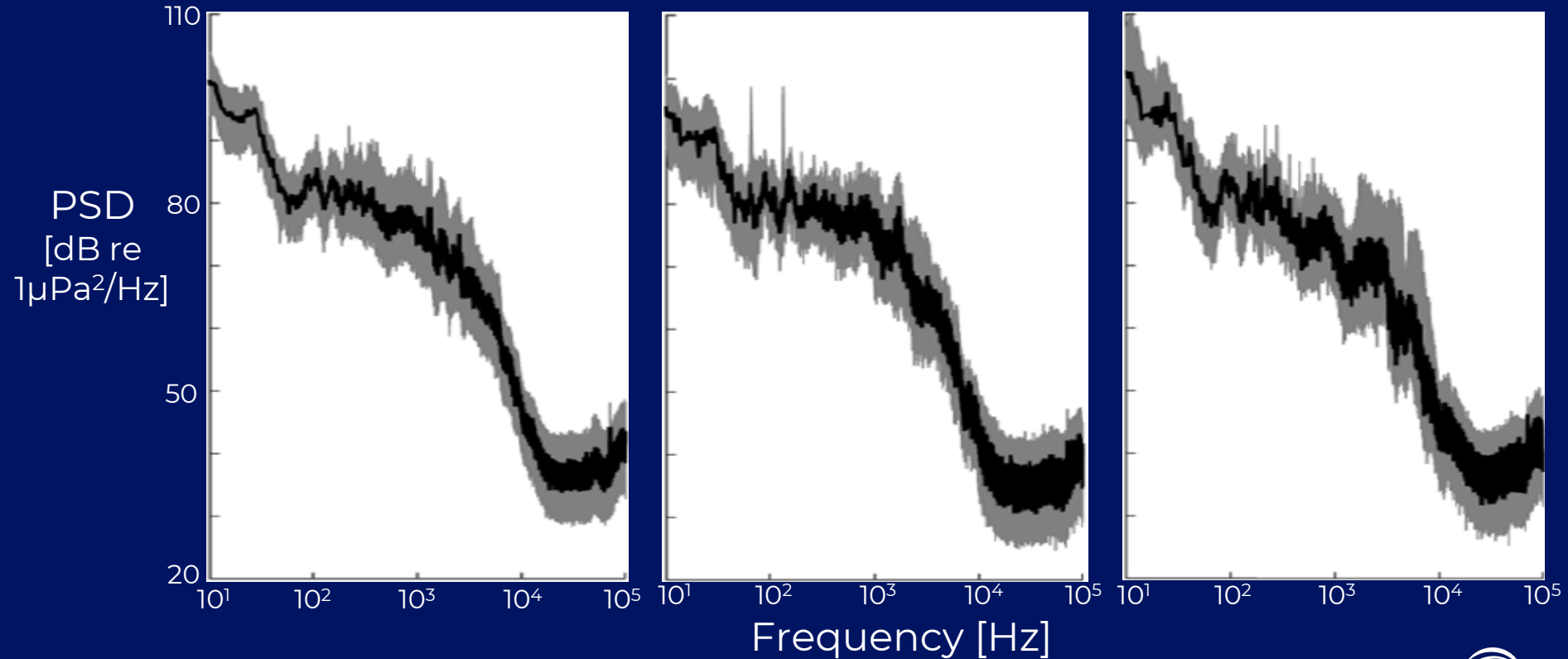
Deployment

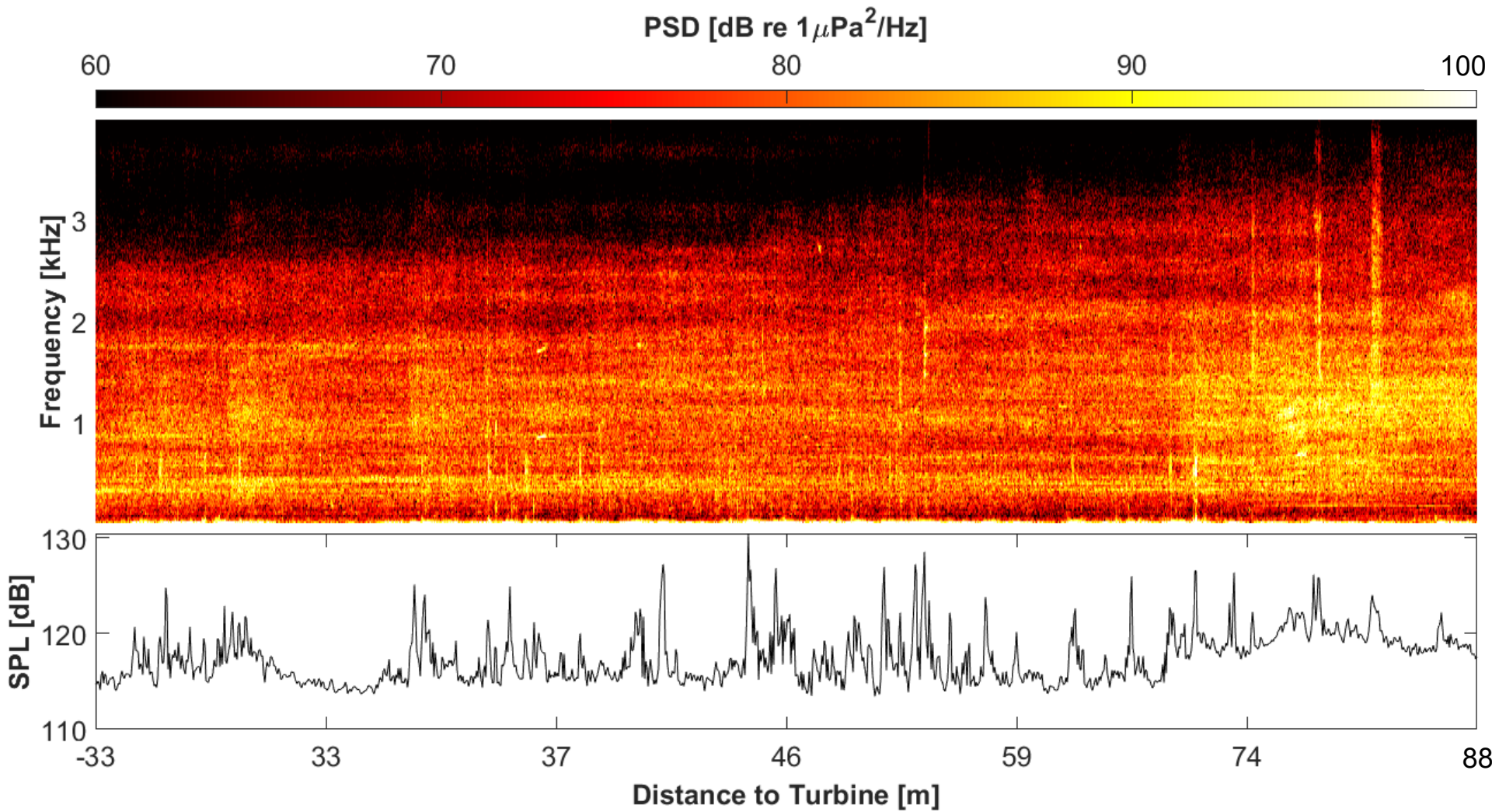


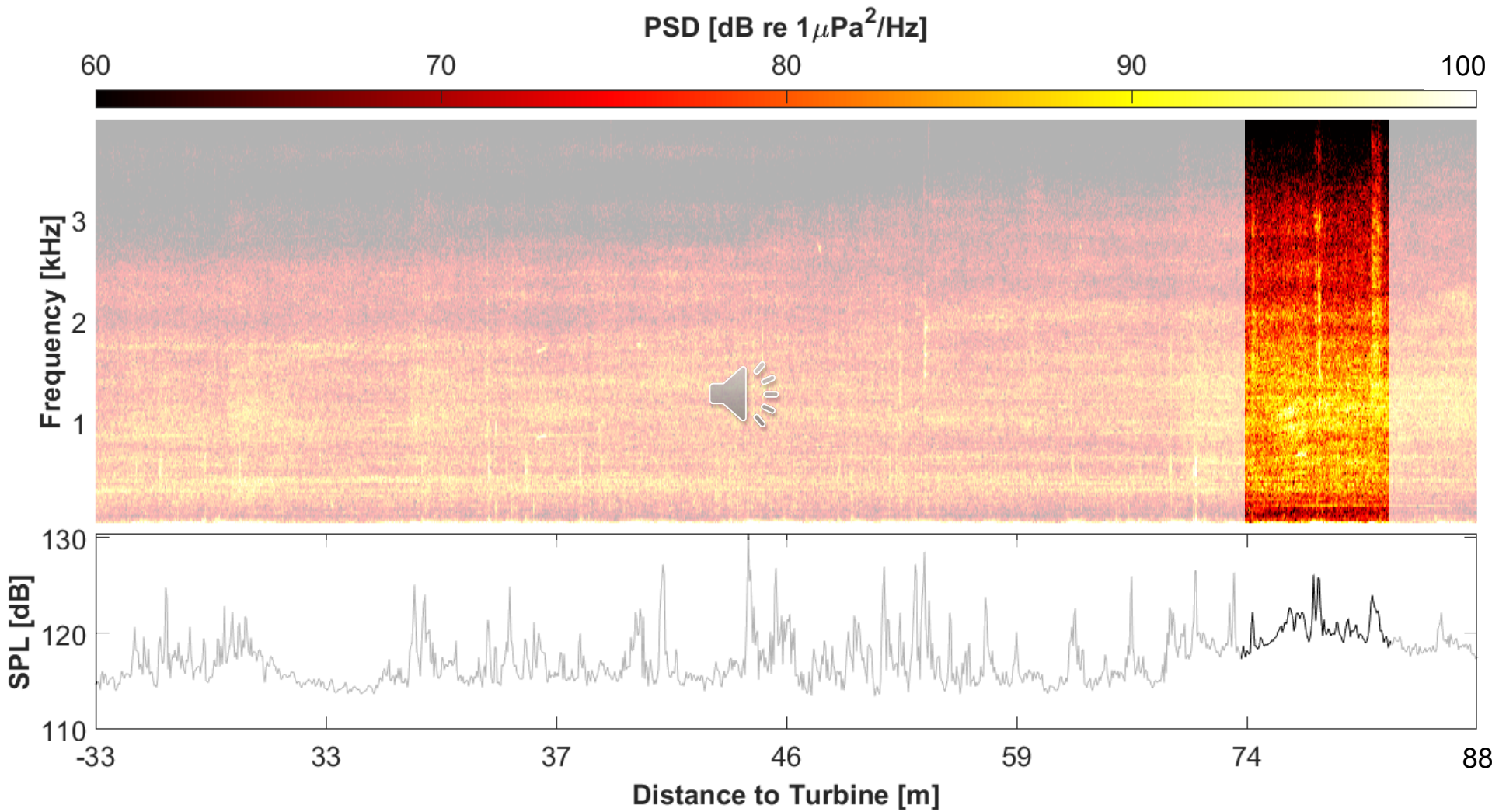
Deployment

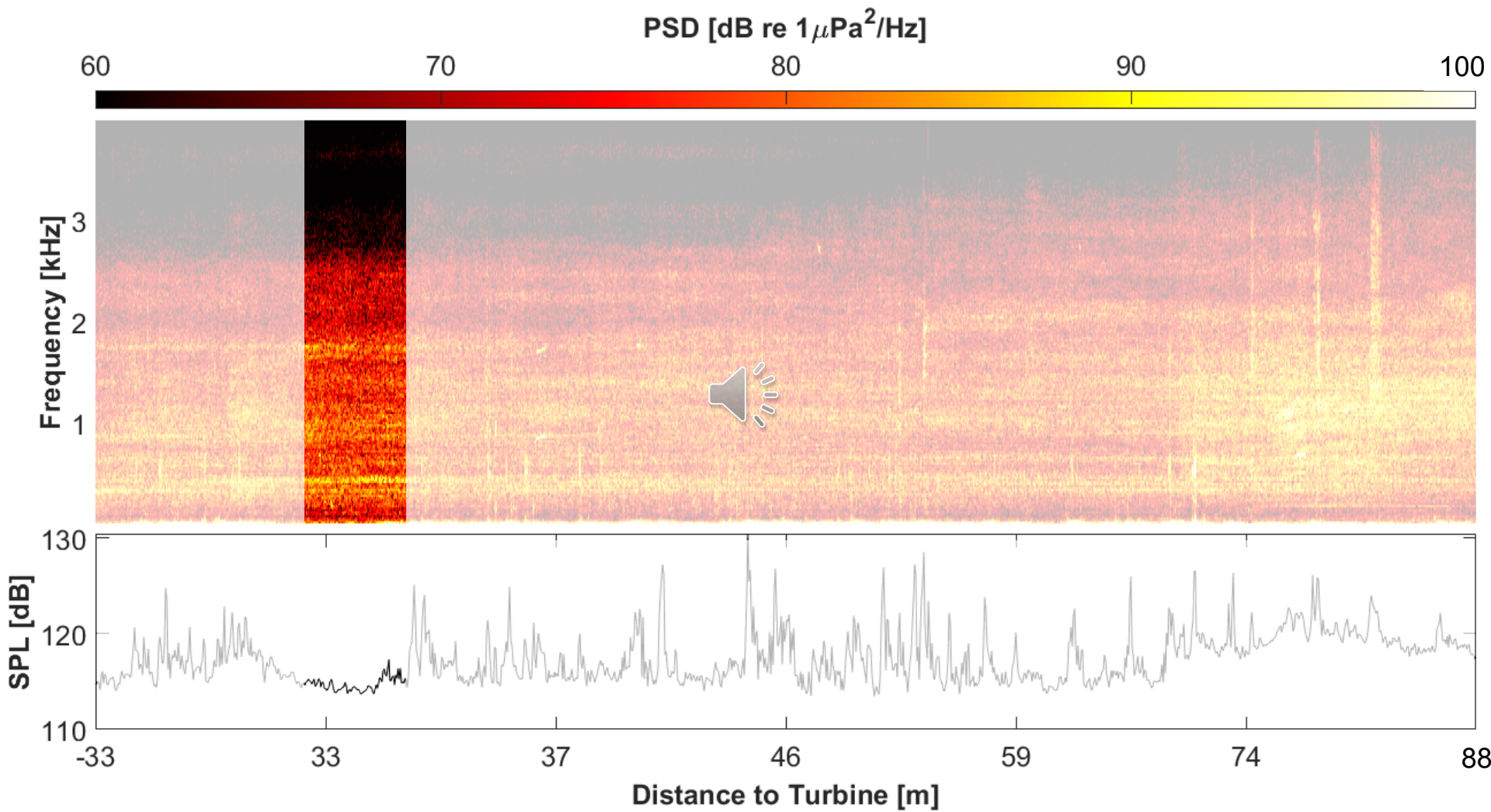


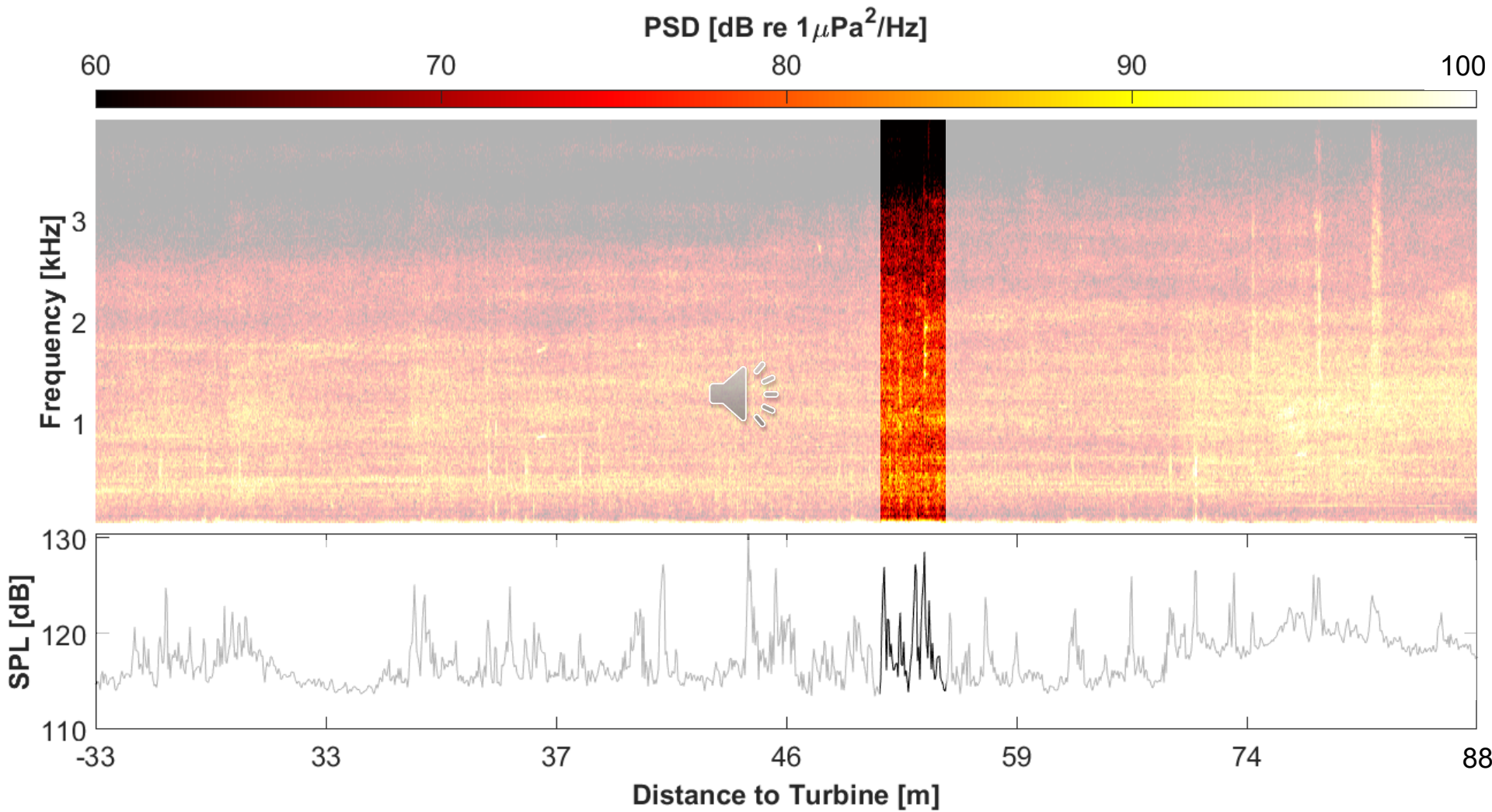
PNNL results



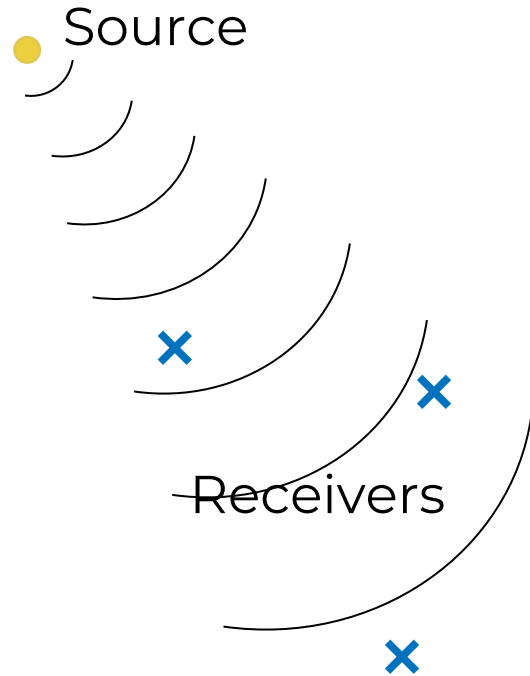




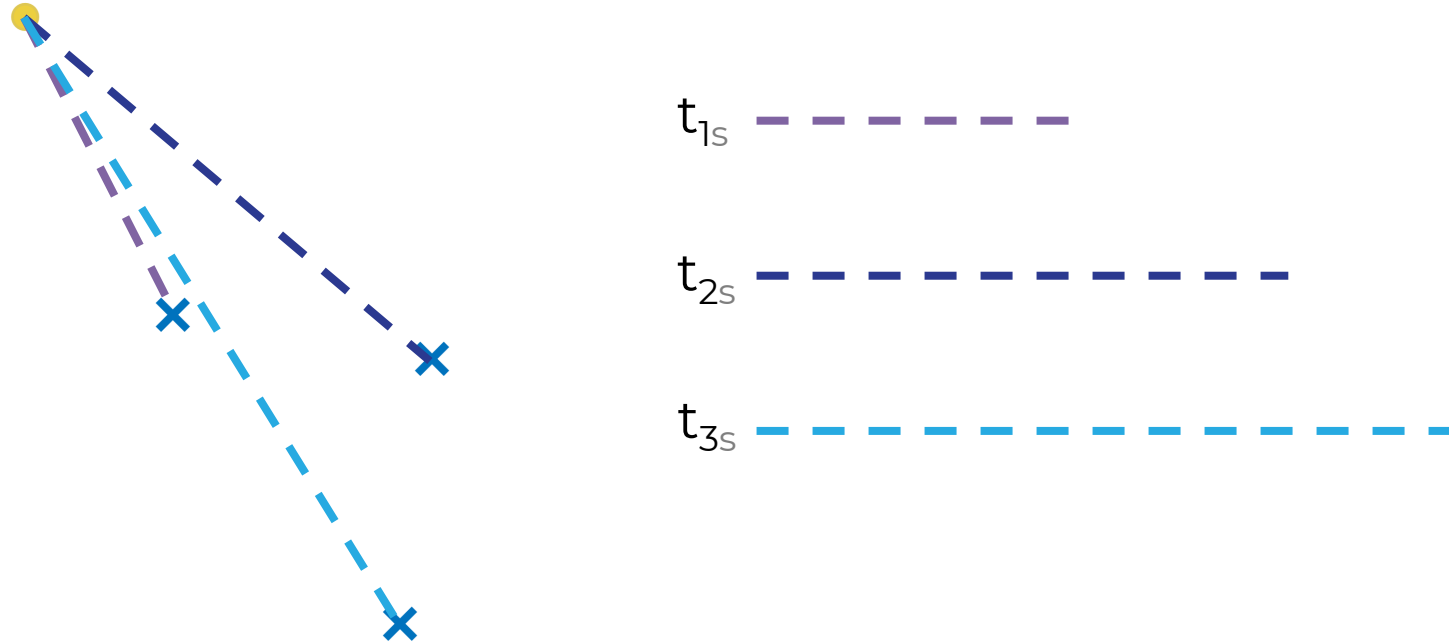




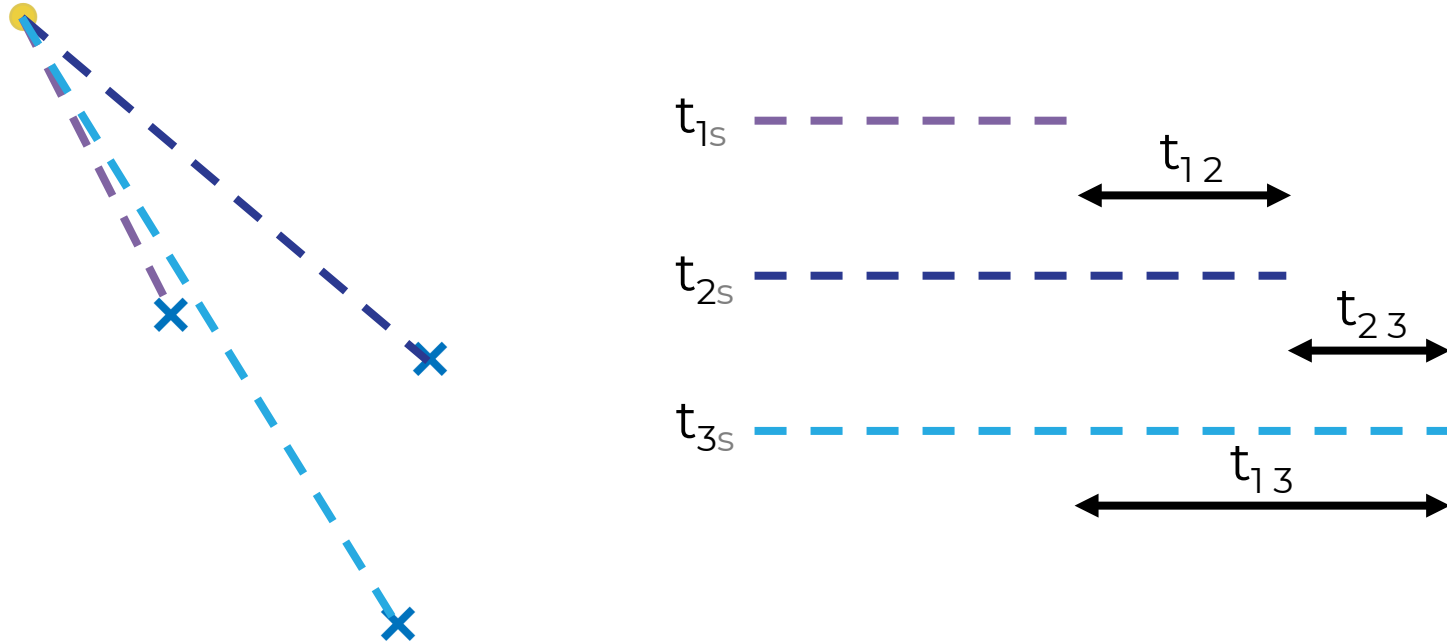
Localization: Time Delay of Arrival

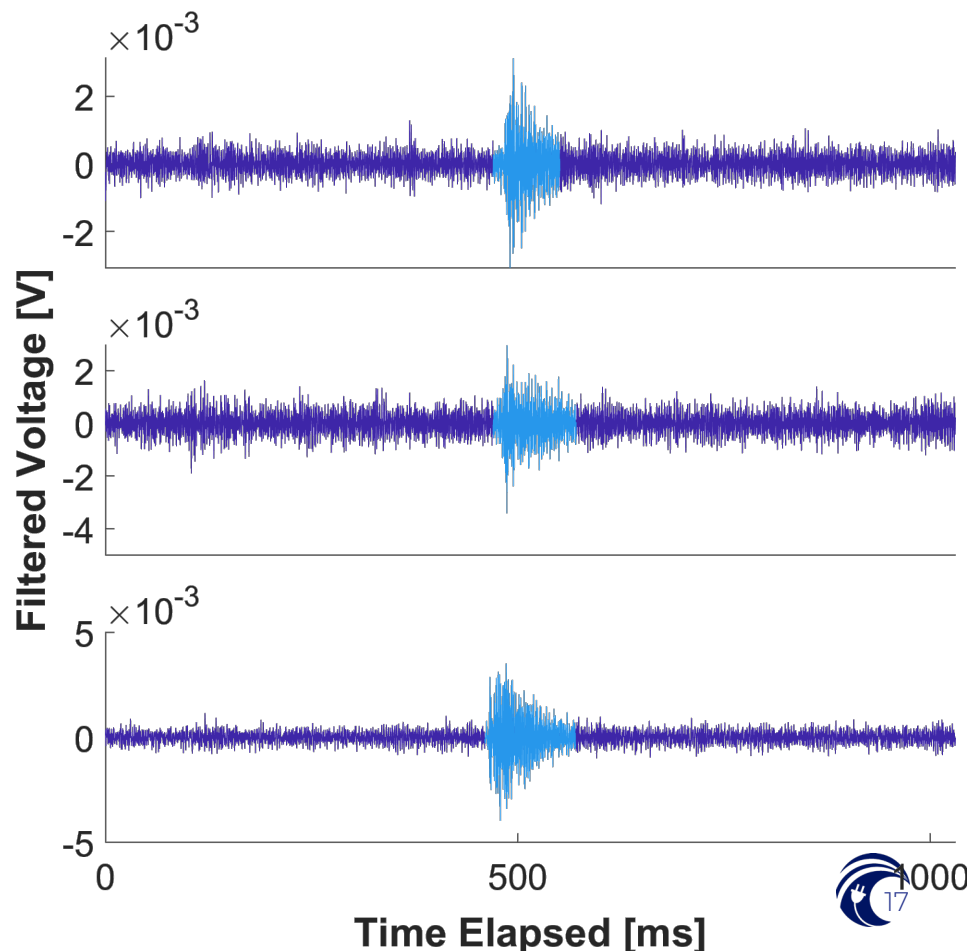
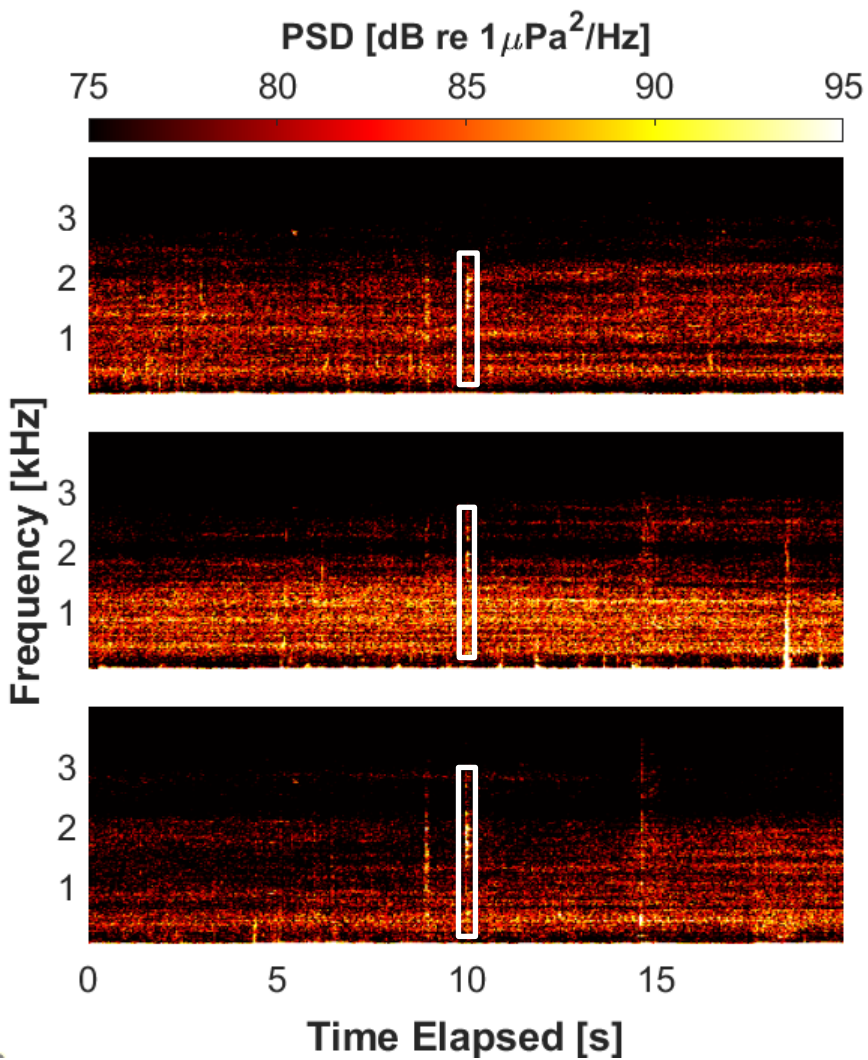


Localization: Time Delay of Arrival

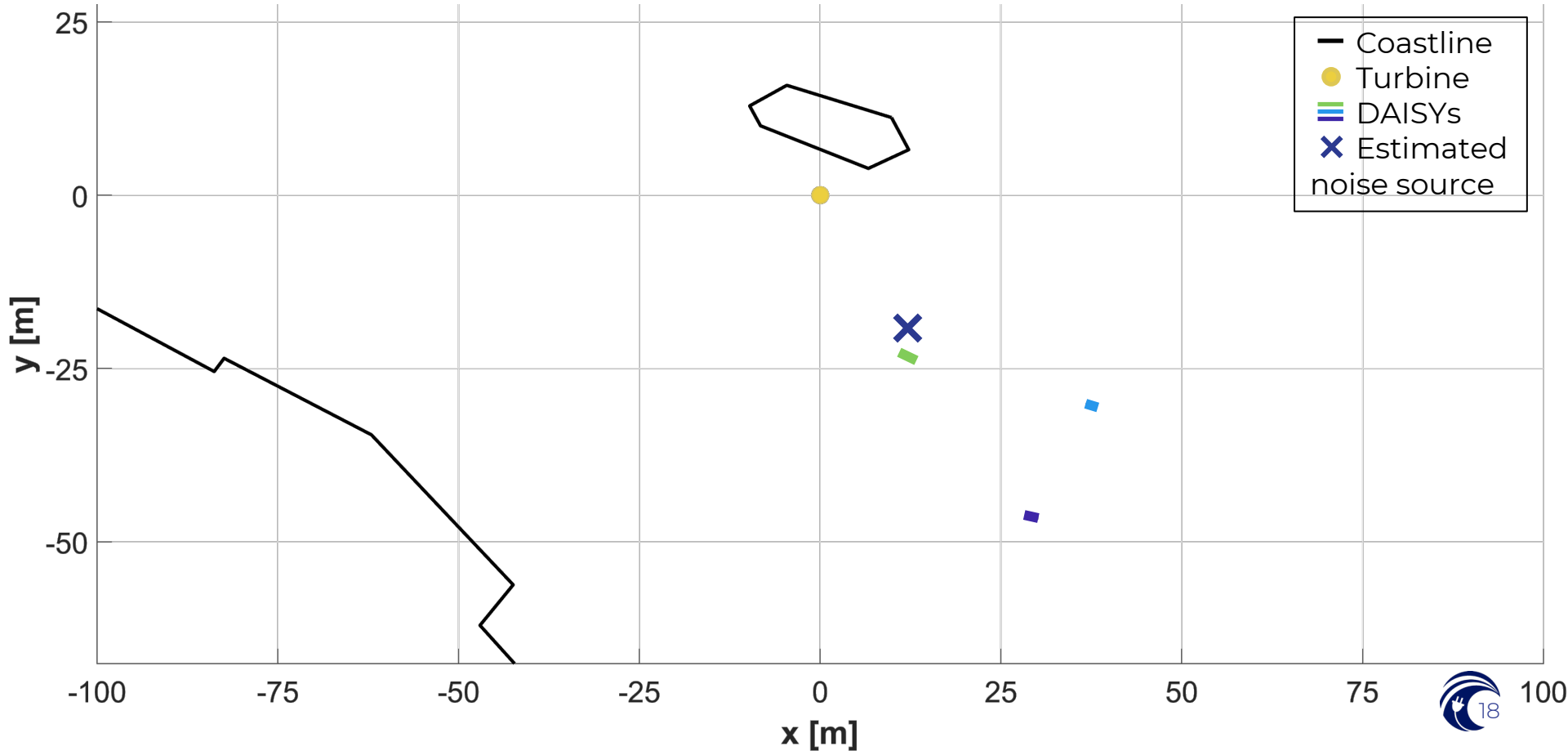


Localization: Time Delay of Arrival

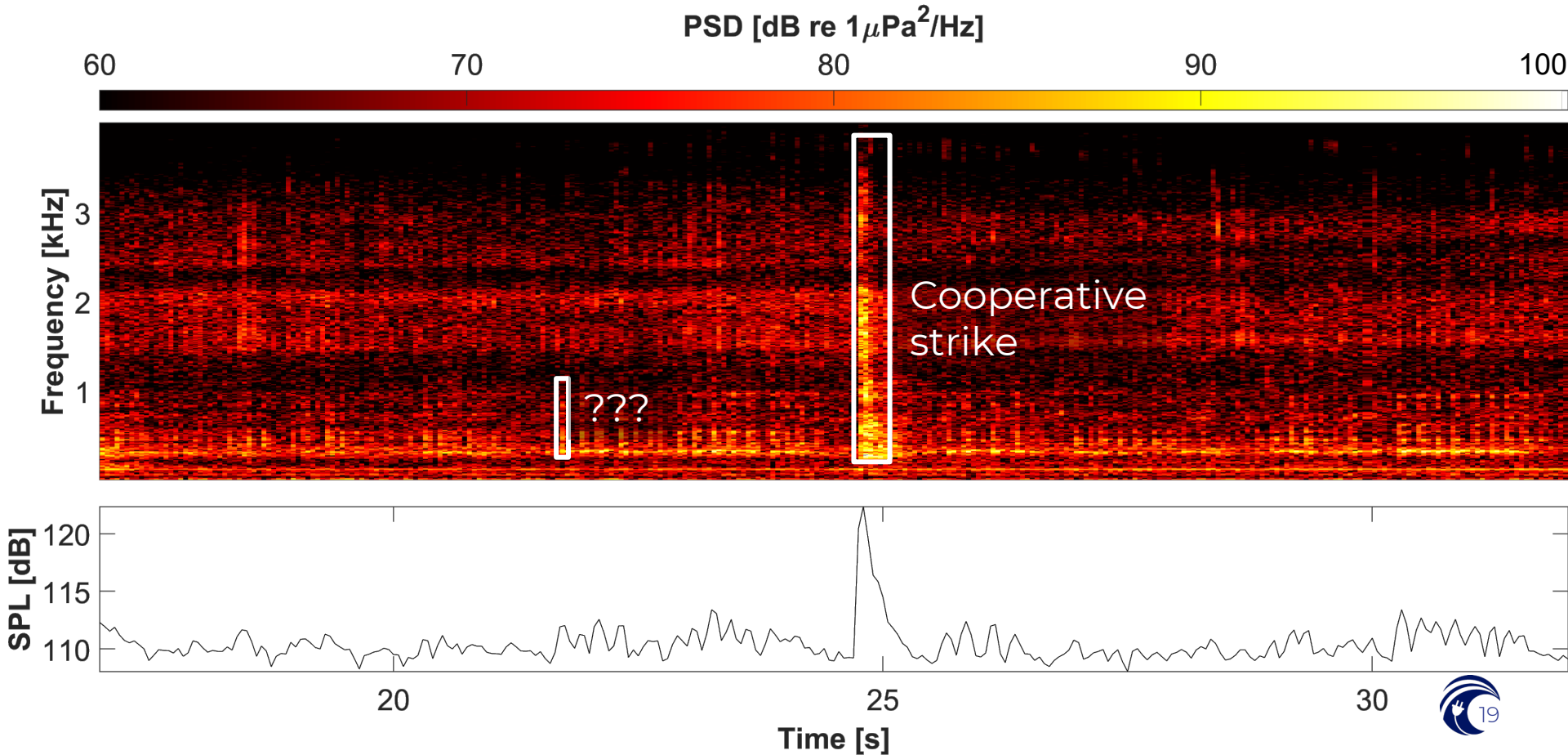




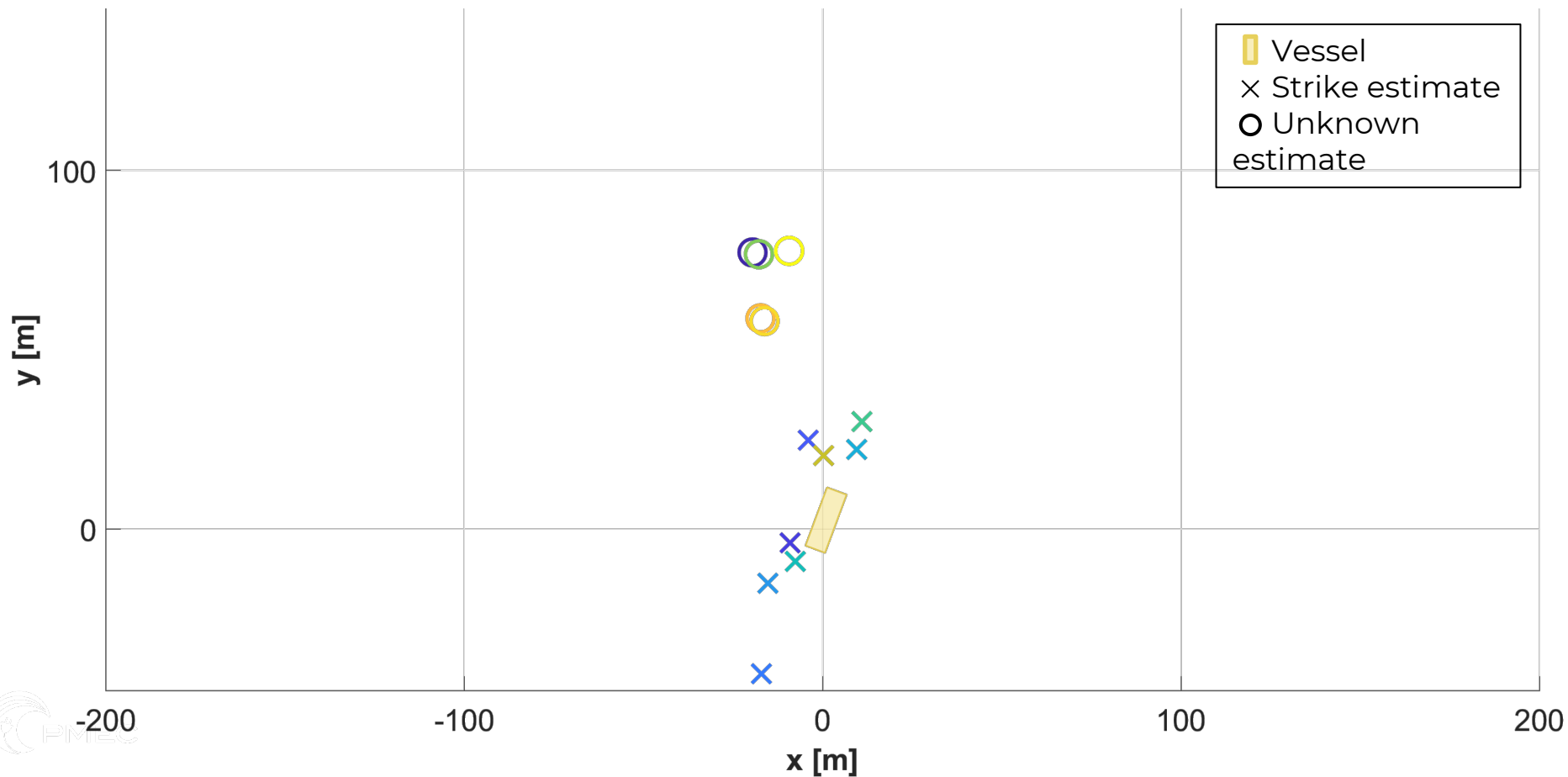
Localization Results Example



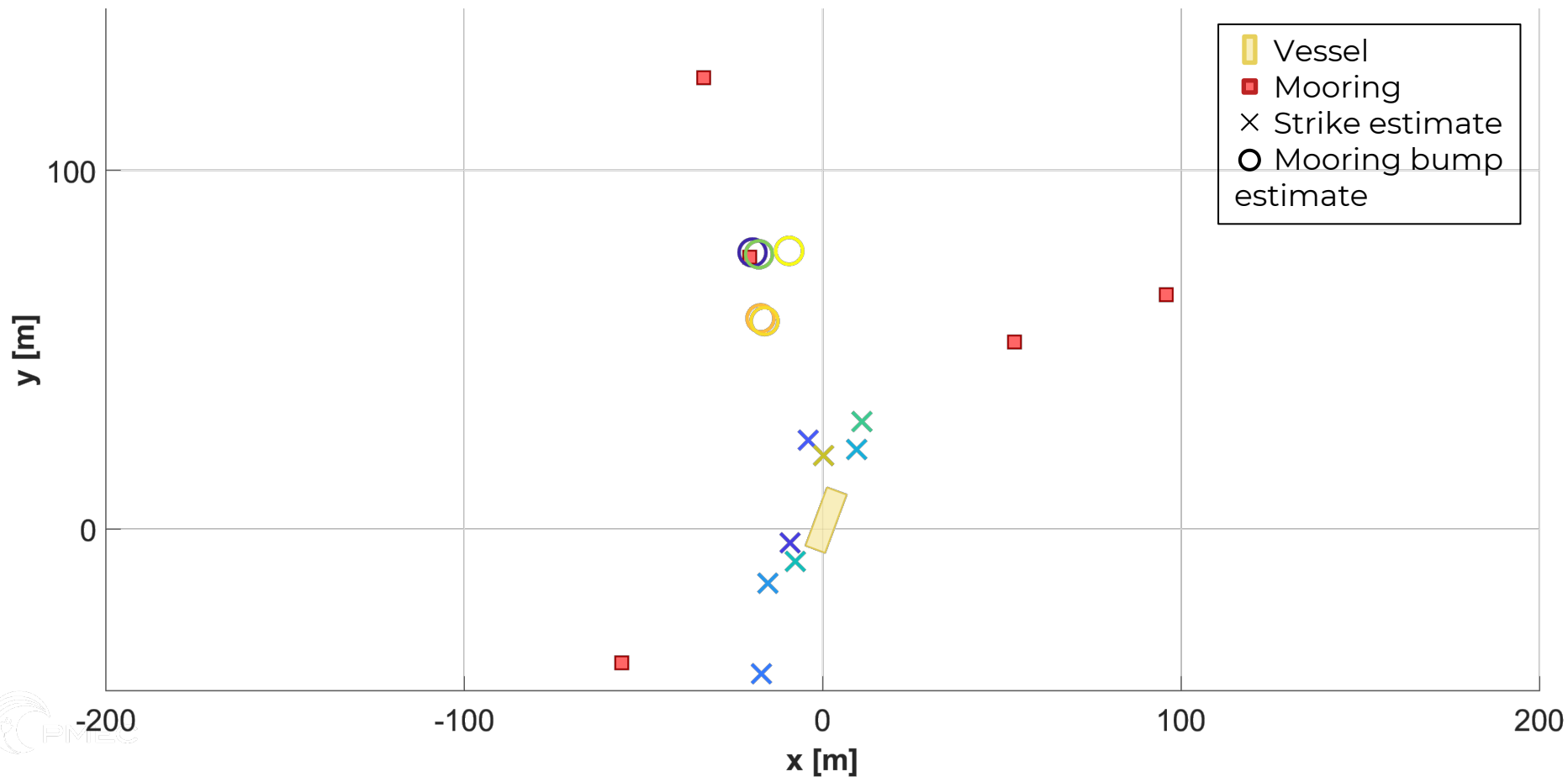
Agate Pass, WA. April 2022



Agate Pass, WA. April 2022



Agate Pass, WA. April 2022



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Questions?

Citations

- University of New Hampshire. (n.d.). *Turbine Deployment Platform Interactive Model*. Portsmouth Memorial Bridge: The Living Bridge. Retrieved July 10, 2022, from <https://livingbridge.unh.edu/bridge-models/interactive-models/interactive-model-platform/>
- Haxel, J., Zang, X., Martinez, J., Polagye, B., Staines, G., Deng, Z. D., Wosnik M., & O'Byrne, P. (2022). Underwater Noise Measurements around a Tidal Turbine in a Busy Port Setting. *Journal of Marine Science and Engineering*, 10(5), 632.
- Sayed, A. H., Tarighat, A., & Khajehnouri, N. (2005). Network-based wireless location: challenges faced in developing techniques for accurate wireless location information. *IEEE signal processing magazine*, 22(4), 24-40.

Localization equations

$$r_{ij} = (t_i - t_j)c$$

$$\begin{bmatrix} x_s \\ y_s \end{bmatrix} = r_{1s} \begin{bmatrix} x_2 & y_2 \\ x_3 & y_3 \end{bmatrix}^{-1} + \begin{bmatrix} -r_{21} \\ -r_{31} \end{bmatrix} + \begin{bmatrix} x_2 & y_2 \\ x_3 & y_3 \end{bmatrix}^{-1} + \frac{1}{2} \begin{bmatrix} x_2^2 + y_2^2 - r_{21}^2 \\ x_3^2 + y_3^2 - r_{31}^2 \end{bmatrix}$$

$$r_{ij} = r_{is} - r_{js} = \sqrt{(x_i - x_s)^2 + (y_i - y_s)^2} - \sqrt{(x_j - x_s)^2 + (y_j - y_s)^2}$$