

## **ThermalTracker-3D**

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## **Project Overview**

### Purpose

- Provide site-specific information on seabird and bat activity.
  - Complement aerial and ship-based surveys
  - Record continuously, day and night, all weather
  - Data: time, species, flight height, flight direction, time in rotorswept-zone, etc.

### Goals

- Reduce uncertainty during siting/permitting
- Improve accuracy of collision risk models with empirical data
  - Activity correlated with environmental conditions
  - Avoidance behavior





## **BOEM Guidelines for Avian Surveys Offshore**

- Identify and confirm which avian species are using the project site, and when these species may be present where development is proposed;
- Establish a pre-construction baseline which may be used to assess whether detectable changes associated with proposed operations occurred in post-construction abundance and distribution of avian species;
- Collect additional information aimed at reducing uncertainty associated with baseline estimates and/or to inform the interpretation of survey results; and
- Develop an approach to quantify any substantial changes in the distribution and abundance of avian species associated with proposed operations.

https://www.boem.gov/sites/default/files/renewable-energy-program/Regulatory-Information/Avian\_Survey\_Guidelines.pdf



### **ThermalTracker-3D Operation**



- 1. Thermal cameras record continuous video.
- 2. Software automatically extracts flight track data in real-time.



20200612-6 03:35.9 northwest 20200612-7 03:42.4 northwest

# Flight track data is transmitted to shore-based server.

		Min	Max	Avg		
	Speed	Height	Height	Height	Species	Confidence
	12.6	30	46	36	Gull	98
	11.5	36	44	40	Gull	97
t	11.3	18	38	27	Tern	82
	12.9	27	39	32	Gull	93
	8.3	64	168	94	Albatross	98
t	12.6	29	43	29	Tern	79
t	10.5	39	53	41	Gull	84



### **ThermalTracker-3D Basic Components**



ThermalTracker-3D software





data link





#### computer







### **ThermalTracker-3D Development Timeline**





#### 2021

### Refine **Operations**

### **TRL 7**

6



### **Land-based Validation**

- Drone flights validated 3D tracking
- Evaluated camera positioning/orientation
- Endurance test

Variable weather conditions

#### FireFly Pro





#### NREL's National Wind Technology Center





## Land-based Prototype (\$25k)





- Positions were transformed to a common coordinate frame
- GPS data were interpolated to coincide with ThermalTracker estimates
- Manuscript submitted for publication



#### **Error\* Statistics**

	Percentile							
Dimension	10 <sup>th</sup>	25 <sup>th</sup>	50th	75 <sup>th</sup>	90 <sup>th</sup>			
Х	-7.3	-5.4	-2.1	2.2	6.1			
Y	-0.3	1.0	3.2	4.3	6.8			
Ζ	-17.2	-6.5	3.0	11.6	19.9			

\*Error = ThermalTracker-3D – GPS (meters) Distances ranged from 50 to 350 meters

N = 18,801



## **2020 Plan: Offshore Validation**

- ThermalTracker-3D will be integrated with a Wind Sentinel buoy
- 25 nautical miles offshore in Humboldt potential lease area
- 1-year deployment starting April 2020
- Observer visits spring, fall to survey

#### **DOE Wind Sentinel Buoy**



**BOEM's Humboldt call** area (approximate)

Wind Profiling Lidar wind speed, direction up to 200 m

Other instrumentation:

- surface wind
- temperature
- ADCP









#### Platform motion



### Harsh environment



Yaw (deg)





### **Offshore Prototype (~\$65k)**



Flir A65 in stainless steel housing





Lucid Triton high-res camera







satellite link



OnLogic Karbon 700



Perfect Horizon stabilization system





## **ThermalTracker-3D Summary**

- Purpose: Collect site-specific seabird (bat) flight activity.
- Use for baseline data collection during siting/permitting.
- Use for operational monitoring to quantify change.
- Reduce uncertainty, improve collision risk models.



### TRL 7

### Refine Operations

### 2021





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